

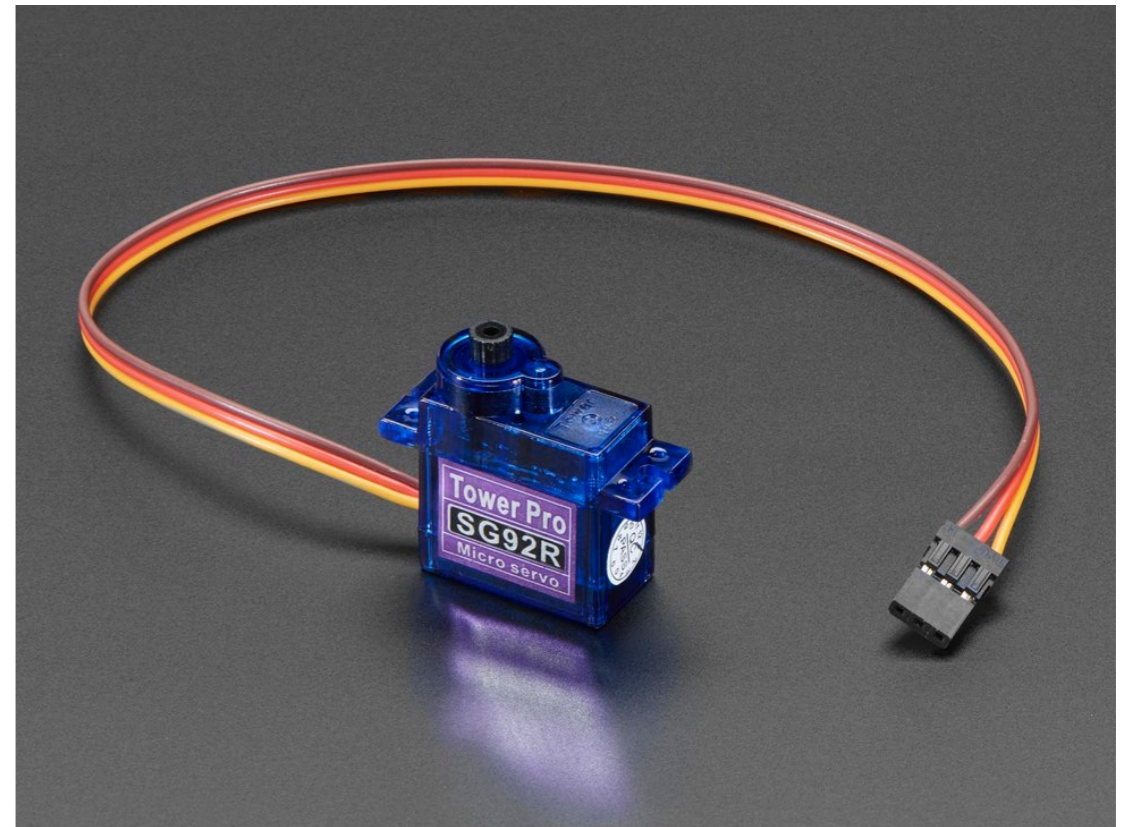
Intro to Servos

Servos are simple motors with a microcontroller built in.

Technically they come in two flavours.

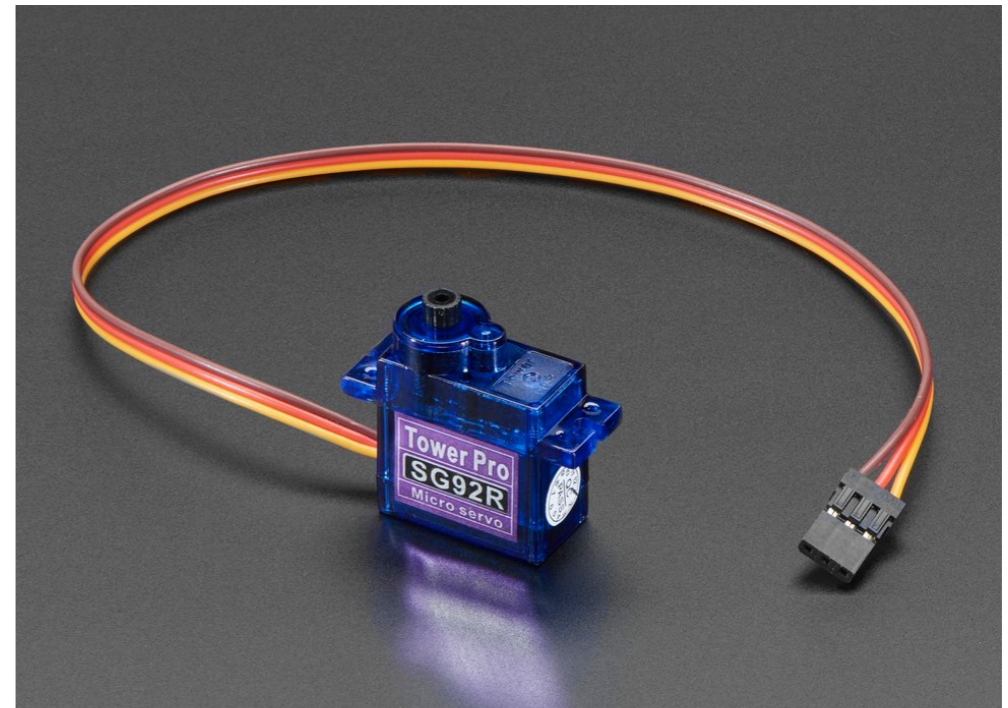
180 degrees & 360 degrees

We have 180 servos.



Servos **differ** from our other motors in **several** important **ways**.

- they only go **halfway** around
- the **motor driver** circuit is **built-in**
- allow for precise control of angular **POS**ition
- there is a **library** for servo control



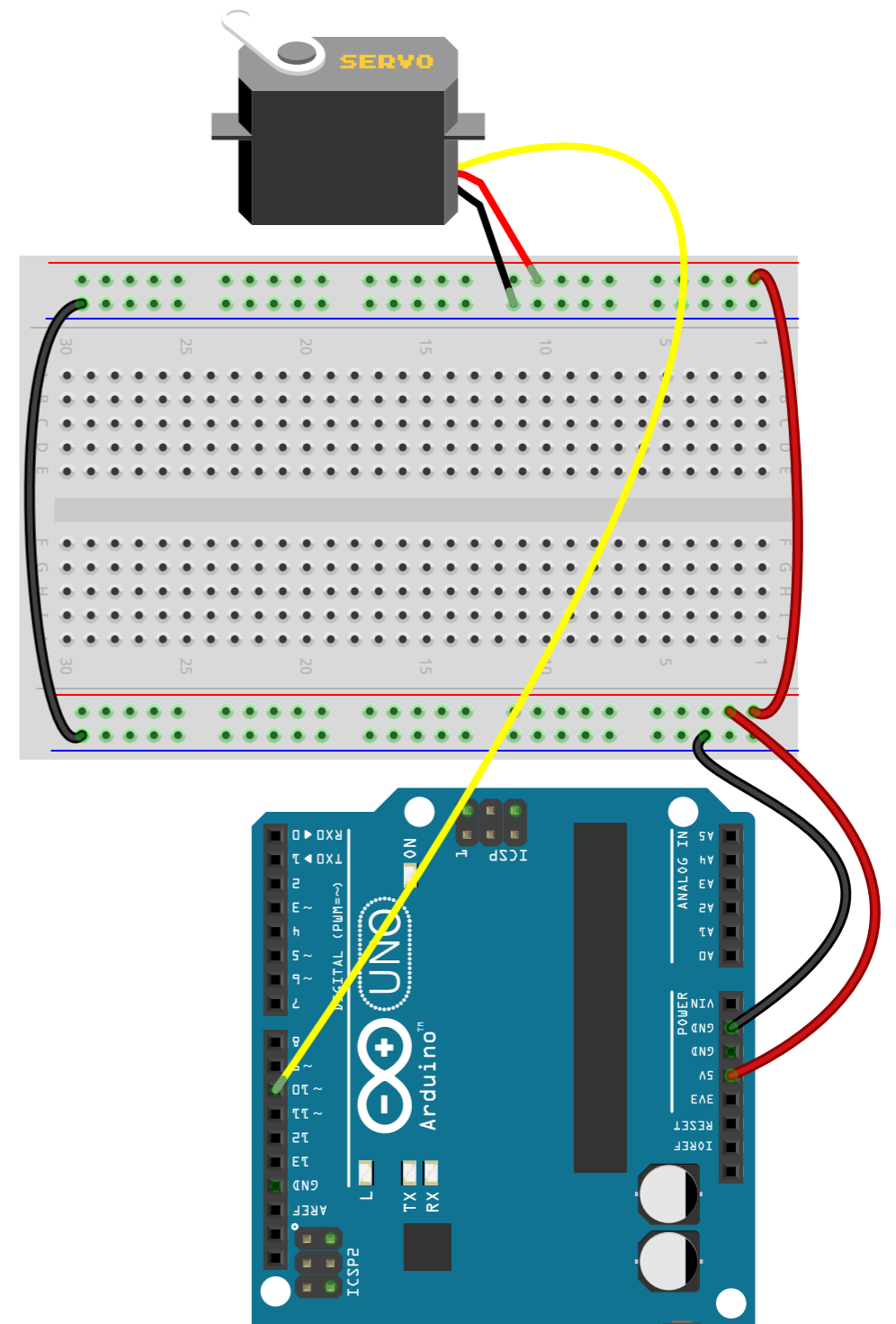
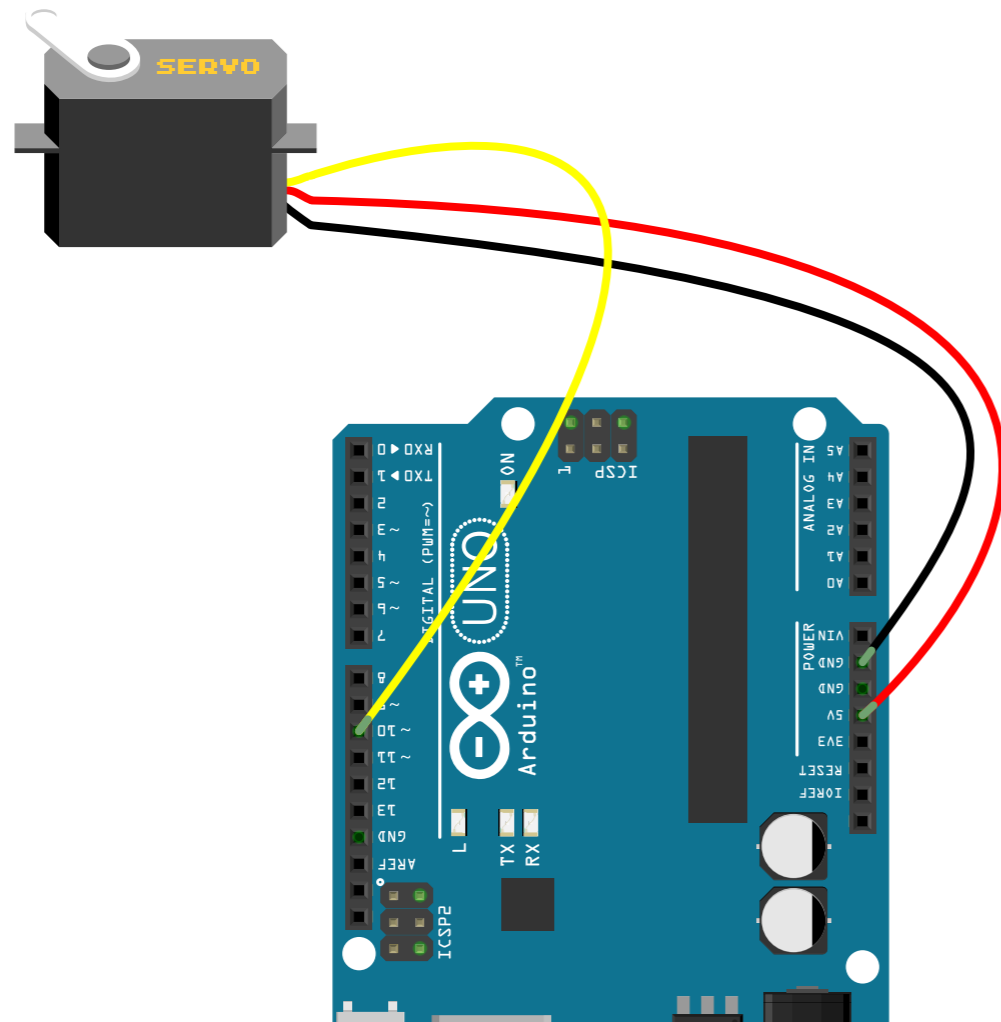
Instead of adding a wheel,

One adds a **HORN** (like a unicorn or rhino)

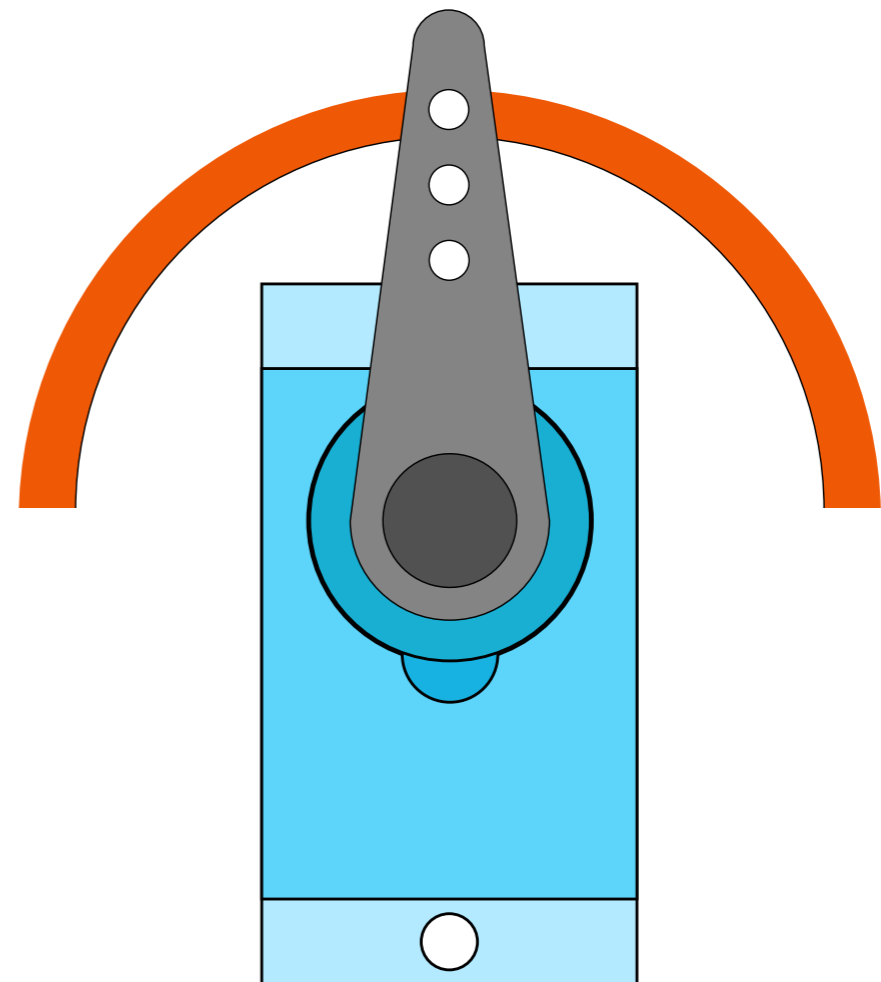
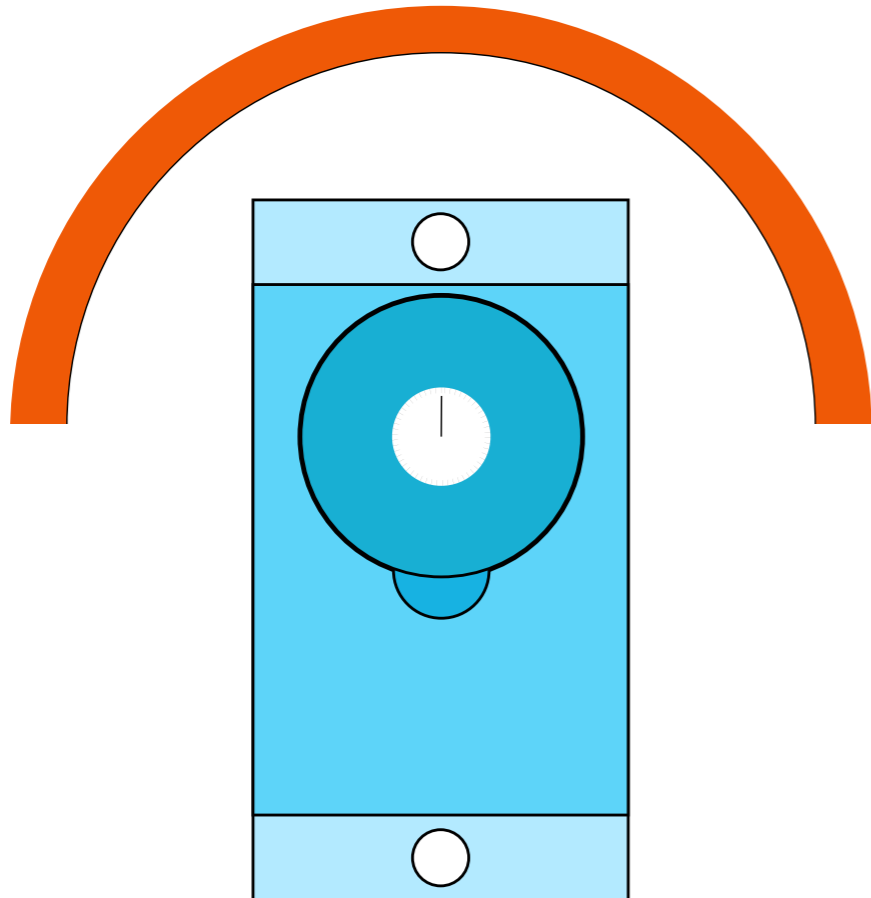
(we don't name these things, but we do make up the bad comparisons)



BROWN wire connects to **GND**
RED wire to **5V**
YELLOW to a digital Pin 10 (SIGNAL)



Get Started — Center servo and attach horn
(orange arc indicates travel of servo)

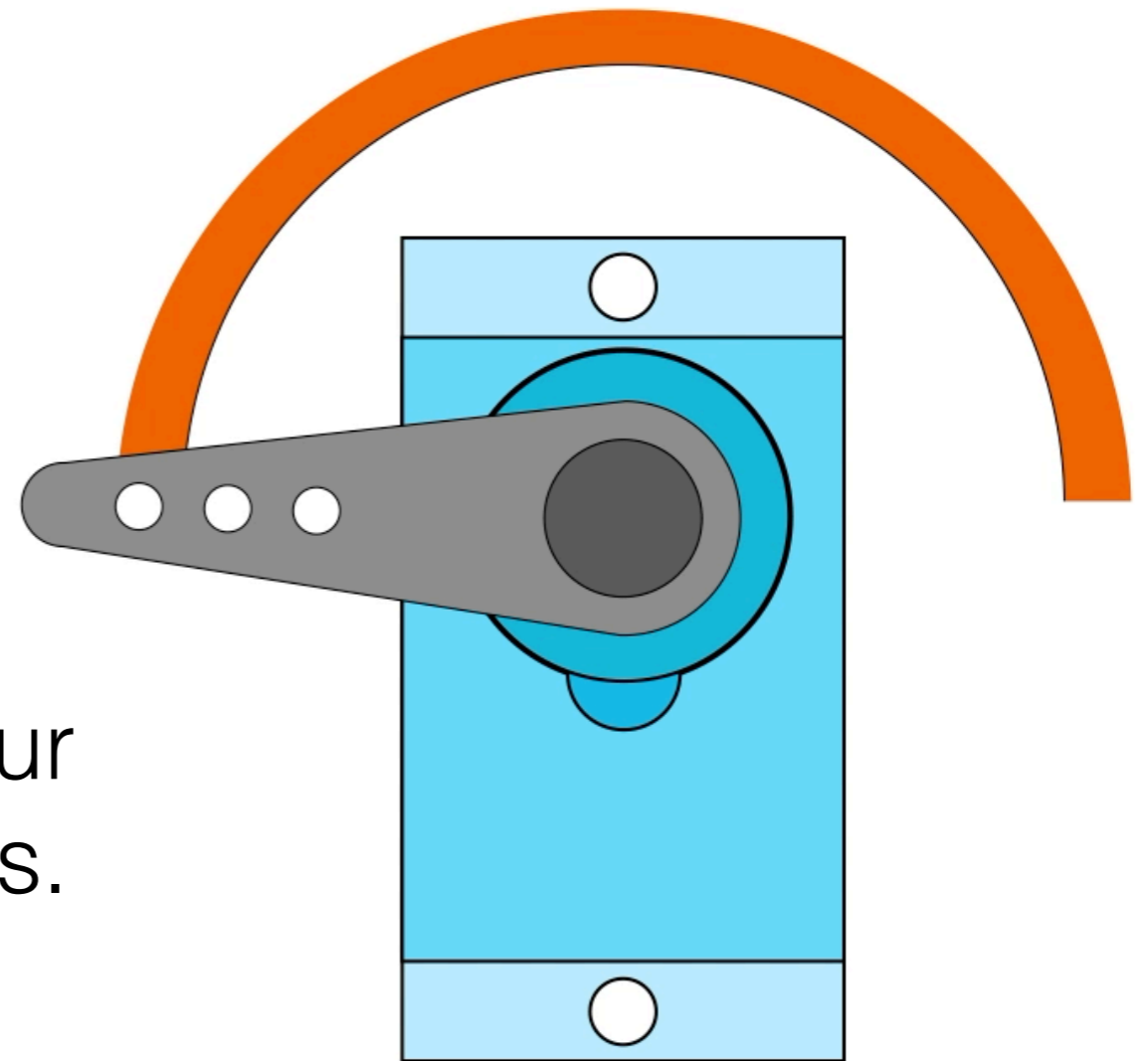


Add CODE

Upload this file:

`_0_centerServo`

Sweep the Servo



Using a **for-loop**, to move our servo through all its positions.

Upload this file:

`_1_SweepServo`

tangibile